

Autonomous Mobile Robots

LD Series

Designed to automate material transport tasks in factories and indoor facilities.

• Natural-feature navigation:

Automatically plans efficient routes and prevents collisions

• Fleet management:

Supervises and coordinates the entire fleet of up to 100 vehicles

· Easy deployment:

Short installation time, no facility modifications



Ordering Information

| Product Name | Maximum Load | Docking Station Kit *1 | Top Plate | Pendant (Joystick) | Part Number |
|----------------------------------|--------------|---------------------------|-----------|--------------------|-------------|
| | | | | 37032-00000 | |
| LD-60 | | Yes | | No | 37032-00002 |
| | COlor | | Yes | | 37032-10004 |
| | 60 kg | | No | | 37032-20000 |
| LD-60 ESD *2 | | Yes | | No | 37032-20002 |
| | | | Yes | | 37032-20004 |
| | | | No | | 37042-00000 |
| LD-90 | | Yes | | No | 37042-00002 |
| | | Yes | | 37042-10004 | |
| | | No | | 37062-00000 | |
| LD-90x *3 | | Yes No | | 37062-00002 | |
| | 00 km | | Yes | | 37062-10004 |
| | 90 kg | No | | 37042-20000 | |
| LD-90 ESD *2 | | Yes No | | 37042-20002 | |
| | | | Yes | | 37042-20004 |
| | | | No | | 37062-20000 |
| _D-90x ESD * 2 * 3 | | Yes No | | No | 37062-20002 |
| | | Yes | | | 37062-20004 |
| | | No | | 37222-00000 | |
| LD-250 | | Yes | Yes No | | 37222-00002 |
| | 250 kg | | Yes | | 37222-10004 |
| | 250 kg | No | | | 37222-20000 |
| LD-250 ESD *2 | | Yes No | | 37222-20002 | |
| | | | Yes | | 37222-20004 |

^{*1.} Includes Battery Power Cable.

Note: 1. To ensure proper fleet management, please contact an OMRON representative before ordering AMRs to add to an existing fleet.

^{*2.} For use in electrostatic-sensitive environments, compliant to the IEC 61340-5-1 standard.

^{*3.} For use in cart transporter applications.

^{2.} The battery for the AMR must be ordered separately (part number 20452-000). Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

Items Included With the AMR

| Item | Description |
|-----------------------|---|
| HMI Jumper | HDB15 male plug |
| Wireless Antennas | Two rubber duck antennas with SMA plugs |
| Labels | Warning and product labels |
| USB drive | Contains digital product documentation and software for operating the AMR |
| Printed Documentation | Printed manuals and guides for unpacking and operating the AMR |

Accessories and Optional Items

| Appearance | Item | Details | Part Number |
|--|---|--|---|
| | EM2100 Appliance | Appliance that runs any Fleet Operations Workspace Solutions software. 120 day factory trial license included. Refer to Fleet Operations Workspace (FLOW) Licenses below for more information. | 20271-900 (Primary Fleet Manager) 20271-901 (Secondary Fleet Manager) 20271-903 (Bundle with Fleet Simulator License) |
| | Mobile I/O Box | Used with a Fleet Manager to summon an AMR to a goal or control connected devices with I/O | 23419-802 |
| - - | Mobile I/O Box Power Supply | Recommended for purchase with the Mobile I/O Box | 23419-812 |
| 4 | High Accuracy Positioning System (HAPS) Single sensor | AMR Alignment using magnetic floor tape. Includes single HAPS sensor kit, one mounting bracket, cabling, hardware, and magnetic tape (254 mm wide, 49 m long) | LD-60/90: 13660-100 LD-250: 21374-100 |
| | High Accuracy Positioning System (HAPS) Double sensor | AMR Alignment using magnetic floor tape. Includes double HAPS sensor kit, two mounting brackets, cabling, hardware, and magnetic tape (254 mm wide, 49 m long) | LD-60/90: 13660-000 LD-250: 21374-000 |
| | Magnetic tape | 25 mm wide magnetic tape (South top side, 49 m roll) | 14925-000 |
| | Acuity Localization | Camera, mounting kit, cables, leveling kit | 13700-000 |
| | | Camera, mounting kit, cables, no leveling kit | 13700-100 |
| | Side Laser Bundle | Includes two Lasers, mounting kit, and cable | 13456-000 |
| | Side Laser Kit | Includes two lasers, two mounting kits, two metal covers, and cable | 13456-100 |
| | Battery * | Removable and rechargeable power source for the AMR. | 20452-000 |
| and the same of th | Docking Station | Used to autonomously charge the battery inside an AMR or to charge an AMR battery outside of the AMR with a battery power cable (sold separately) | 12477-000 |
| | Battery Power Cable | Cable length: 0.45 m | 12676-000L |
| | Pendant (Joystick) | Handheld device for manually driving an AMR and map creation, 3 m cable length | 13558-000 |

| Appearance | Item | Details | Part Number |
|------------|-------------------------------------|---|-------------|
| | Digital I/O Terminal Block Kit | Provides a terminal block for the Digital I/O connector on the Core. Includes a 0.76 m male to female cable, terminal block, and a mounting bracket | 14165-000 |
| | Top Plate - LD-60, LD-90, LD-90x | Provides additional protection for the AMR. | 12944-000 |
| | Top Plate - LD-250 | Describes a different sector for the AMD | 20458-002 |
| | Top Plate - LD-250 ESD | Provides additional protection for the AMR. | 20458-202 |
| | Rear Facing Laser Bundle | Provides CAPS functionality while the AMR is traveling in the reverse direction. Includes TiM laser and required cables. | 21446-000 |

^{*}Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

Software Licenses

| Product Name | Applicable For | Configuration | Part Number |
|---|----------------|--|----------------------|
| Fleet Operations Workspace (FLOW) Core Fleet Manager License, 3 Year | | Initial entitlement for a 3 year renewable FLOW Core license. Replace □□ with 05, 10, 15, 20, 25, 30, 50 to indicate the number of AMRs licensed to connect, where 50 represents an unlimited number of AMRs. | 30271-1□□ *1 |
| Fleet Operations Workspace (FLOW) Core Fleet Upgrade | Virtual Fleet | Entitlement for fleet connection limit increase by one additional AMR (used for existing installations). | 30271-001 |
| Fleet Operations Workspace (FLOW) Core Renewal | Manager | Entitlement for a 1 year (verify) renewal of the FLOW Core license. Replace \(\pi\) with a value of 05 to 30, or 50 to indicate the number of AMRs licensed to connect, where 50 represents an unlimited number of AMRs. | 30271-2□□ |
| Fleet Operations Workspace (FLOW) | | Entitlement for a 1 year renewable FLOW iQ license. | 30271-701 |
| iQ License | | Entitlement for a 3 year renewable FLOW iQ license. | 30271-703 |
| Primary Fleet Operations Workspace (FLOW) Core License, 1 Year | EM2100 | Entitlement for a 1 year renewable Primary FLOW Core license, runtime and development, per AMR connection | 20271-800 * 2 |
| Primary Fleet Operations Workspace (FLOW) Core License, 5 Year | | Entitlement for a 5 year renewable Primary FLOW Core license, runtime and development, per AMR connection | 20271-806 *2 |
| Secondary Fleet Operations Workspace (FLOW) Core License, 1 Year | | Entitlement for a 1 year renewable Secondary FLOW Core license per fleet, redundant runtime | 20271-802 *2 |
| Secondary Fleet Operations Workspace (FLOW) Core License, 5 Year | | Entitlement for a 5 year renewable Secondary FLOW Core license per fleet, redundant runtime | 20271-807 *2 |
| License, Fleet Operations Workspace | | Entitlement for a 1 year renewable FLOW iQ license | 20271-701 |
| iQ | | Entitlement for a 5 year renewable FLOW iQ license | 20271-705 |
| Cell Alignment Positioning System (CAPS) License | AMR | AMR Alignment using software-defined target. Entitlement for a perpetual CAPS license | 20271-805 |

^{*1.} After expiration of a FLOW Core Fleet Manager license, all Virtual Fleet Manager functionality will continue to operate without requiring subscription renewals. An active subscription will still be required to access subsequent software releases, including bug fixes, feature upgrades, and performance improvements.

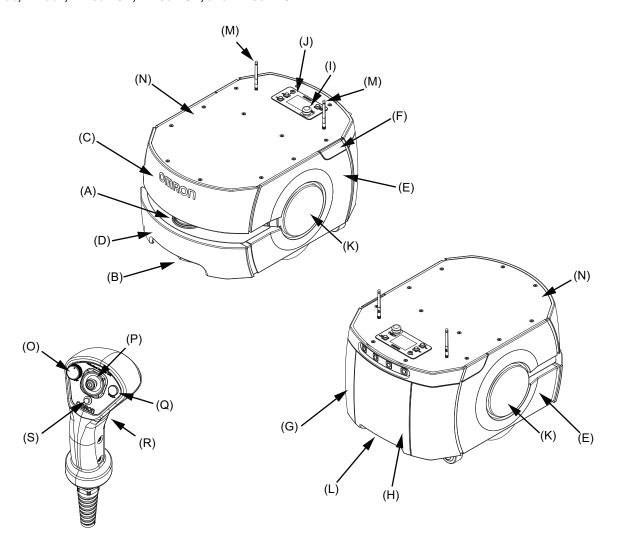
Note: To upgrade to the latest version of the FLOW Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

^{*2.} Expiration of a 1 year subscription license without renewal will result in cessation of the EM2100 fleet management functions of the OMRON AMR solution until the license is renewed. This does not apply to Virtual Fleet Manager.

After five consecutively licensed years (either one 5 year license or five 1 year licenses), all EM2100 fleet management functions will continue to operate without requiring subsequent subscription renewals. An active subscription will still be required to access new software releases, including bug fixes, feature upgrades, and performance improvements.

Features and Components

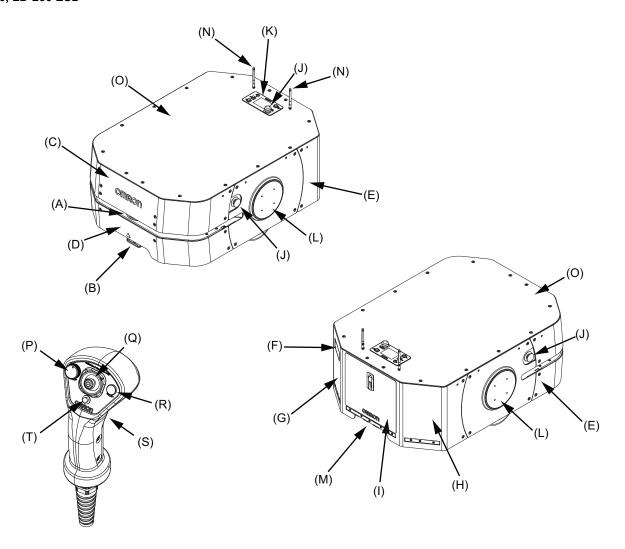
LD-60, LD-90, LD-90x, LD-60 ESD, LD-90 ESD, and LD-90x ESD



| Item | Description | Item | Description |
|------|----------------------|------|--|
| Α | Safety Laser Scanner | K | Light Disk |
| В | Low Laser | L | Charging Contacts |
| С | Upper Front Skin | М | Wireless Antennas |
| D | Bumper Skin | N | Payload Mounting Surface (Top Plate shown) |
| Е | Side Skin | 0 | Speed Control |
| F | Access Panel | Р | Directional Control Stick |
| G | Rear Skin | Q | Goal Button |
| Н | Battery Door Skin | R | Trigger |
| I | E-STOP button | S | Indicator Light |
| J | Operator Panel | | |

Features and Components

LD-250, LD-250 ESD



| Item | Description | Item | Description |
|------|----------------------|------|--|
| Α | Safety Laser Scanner | K | Operator Panel |
| В | Low Laser | L | Light Disk |
| С | Upper Front Skin | М | Charging Contacts |
| D | Bumper Skin | N | Wireless Antennas |
| Е | Side Skin | 0 | Payload Mounting Surface (Top Plate shown) |
| F | Access Panel | Р | Speed Control |
| G | Left Rear Skin | Q | Directional Control Stick |
| Н | Right Rear Skin | R | Goal Button |
| I | Battery Door Skin | S | Trigger |
| J | E-STOP button | Т | Indicator Light |

Specifications

| ,, | 1-90x, LD-60 ESD, LD-90 ESD | LD-60 | LD-90 | LD-90x | | | | |
|--------------------|---|--|--|----------------------------------|--|--|--|--|
| Woight (with Potts | | | FD-90 | LD-90X | | | | |
| Weight (with Batte | Ambient temperature | 62 kg 5 to 40°C | | | | | | |
| | Ambient temperature Ambient humidity | 5 to 95% (non-condensing) | | | | | | |
| | Ambient numbers | Indoor usage only, no excessive dust, no corrosive gas or liquid. Floor must be free of | | | | | | |
| Environment | Operating Environment | water, oil, dirt, and debris. | | safety laser false positives. | | | | |
| | Ingress Protection Class | | IP20 | | | | | |
| | Cleanroom rating | ISO 5 / Class 100 | | | | | | |
| | Minimum floor flatness | F _F 25 (ACI 117 standard) | , | | | | | |
| | Traversable step | 15 mm max. * 1 | 10 mm max. * 1 | | | | | |
| Floor Conditions | Traversable gap | 15 mm max. * 2 | Up to 60 kg: 4.8° / 8.3% incline | | | | | |
| rioor conditions | Maximum Slope | Over 60 kg: 4.8° / 8.3% incline Over 60 kg: Level floor only | | | | | | |
| | Minimum floor compressive strength | 5 Mpa | | | | | | |
| | Routing | Autonomous routing by loc mapping | alizing with safety scannin | g laser based on environment | | | | |
| Navigation | Environmental map making method | Scan by walking the AMR MobilePlanner software | through the environment, a | and upload the scan data to the | | | | |
| - | Low Front Laser | One Class 1 laser at front | of AMR with a 126° field of | view | | | | |
| | Side Laser (optional) | Two Class 1 lasers with a mounted | 270° field of view on the si | des of payload structure, user- | | | | |
| Visual Indicators | | Light discs are located on | the sides of the AMR. Add | itional indicators can be added. | | | | |
| Payload | Maximum Weight | 60 kg | 90 kg | | | | | |
| - | Run time (no payload) | 15 h approx. | - | 20 h approx. | | | | |
| | Run Time (full payload) | 12 h approx. | | 15 h approx. | | | | |
| | Maximum Speed | 1800 mm/s | 1350 mm/s | 900 mm/s | | | | |
| | Maximum Rotation Speed | 180 °/s | | , | | | | |
| Mobility | Stop Position Repeatability (single AMR) *3 | To a position: ±65 mm To standard target: ±25 mm, ±2° With CAPS: ±8 mm, ±0.5° With HAPS: ±8 mm, ±0.4° | | | | | | |
| | Stop Position Repeatability (Fleet) *3 | To a position: ±85 mm To standard target: ±35 mm, ±2° With CAPS: ±12 mm, ±0.5° With HAPS: ±10 mm, ±0.5° | | | | | | |
| Drive wheels | Materials | Solid aluminum with non-n | narking, non-conductive, fo | pam-filled rubber tread | | | | |
| Passive casters | Materials | Conductive thermoplastic | ubber on polyolefin | | | | | |
| Auxiliary Power | | 5 VDC±5%, 1 A switched Aux power 12 VDC±5%, 1 A switched Aux power 20 VDC±5%, 1 A switched Aux power 22 to 30 VDC, 4 A switched 22 to 30 VDC, 10 A switched 22 to 30 VDC, 10 A safe, switched 10 A switched and 10 A safe switched are from the same source and pass through the same 10 A fuse, so the sum of their current must be less than 10 A. | | | | | | |
| | AMR | EN ISO 12100, EN ISO 136 CSA Z434, EN 61000-6-2, | | 25, ANSI B56.5, ISO 10218/ | | | | |
| Standards | Battery | EN ISO 12100, UN 38.3, E | N 61000-6-2, EN 61000-6- | -4, UL 2271 | | | | |
| | Docking Station | EN ISO 12100, UL1012/CS | SA C22.2.107.2, IEC 60204 | 4-1, EN 61000-6-2, EN 61000-6-4 | | | | |
| | Wireless | IEEE 802.11 a/b/g | | | | | | |
| Safety Features | Safety Scanning Laser | One at front of AMR Class 1 PLd safety per ISO13849- 240° field of view | 1 | | | | | |
| | E-STOP Buttons | One on Operator Panel, ac structure | dditional E-STOP buttons o | can be added to the payload | | | | |
| | Rear Sonar | Two at rear of AMR, 2 m rai together. | Two at rear of AMR, 2 m range. Each pair includes one emitter and one receiver working together. | | | | | |
| | Front Bumper | Two pairs of sensors at the front of the AMR | | | | | | |
| | Audible Indicators | Two speakers are included. Additional buzzers can be added. | | | | | | |

| Item | | LD-60 | LD-90 | LD-90x | | | | |
|----------------|-------------|--|---|--------|--|--|--|--|
| Operator | Display | 8.89 cm diagonal TFT, 320 x 240 pixels, color screen | | | | | | |
| Interface | Button | ON button, OFF button, Brak | ON button, OFF button, Brake-release button, and keyed mode selection | | | | | |
| | Wireless | 802.11 a/b/g | | | | | | |
| | Ethernet | One TCP/UDP interface (maintenance LAN), Auto-MDIX | | | | | | |
| User Interface | Serial | Two serial communication interfaces | | | | | | |
| | Digital I/O | 16 inputs, 16 outputs | | | | | | |
| | Audio | Digital audio in / out | | | | | | |

^{*1.} A speed of 250 mm/s is recommended for traversing steps, and routine driving over steps should be avoided. Lower speeds may not traverse the step. Faster or frequent driving over steps will shorten the lifespan of the drivetrain components. All steps should have smooth, rounded

LD-250, LD-250 FSD Specifications

| | Item | LD-250 | | | |
|--------------------|---|---|--|--|--|
| Weight (with batte | ry) | 148 kg | | | |
| | Ambient temperature | 5 to 40°C | | | |
| | Ambient humidity | 5 to 95% (non-condensing) | | | |
| Environment | Operating Environment | Indoor usage only, no excessive dust, no corrosive gas or liquid. Floor must be free of water, oil, dirt, and debris. Direct sunlight may cause safety laser false positives. | | | |
| | Ingress Protection Class | IP20 | | | |
| | Cleanroom rating | ISO 5 / Class 100 | | | |
| | Minimum floor flatness | Fr25 (ACI 117 standard) | | | |
| | Traversable step | 10 mm max. *1 | | | |
| Floor Conditions | Traversable gap | 15 mm max. *2 | | | |
| ioor conditions | Maximum Slope | Max. 1.7° / 3% incline | | | |
| | Minimum floor compressive strength | 5 Mpa | | | |
| Navigation | Routing | Autonomous routing by localizing with safety scanning laser based on environment mapping | | | |
| | Environmental map making method | Scan by manually driving the AMR through the environment, and upload the scan data to the MobilePlanner for map creation. | | | |
| | Low Front Laser | One Class 1 laser at front of AMR with a 126° field of view | | | |
| | Side Laser (optional) | Two Class 1 lasers with a 270° field of view on the sides of payload structure, user-mounted | | | |
| Visual Indicators | | Light discs are located on the sides of the AMR. Additional indicators can be added. | | | |
| Payload | Maximum Weight | 250 kg | | | |
| | Run time (no payload) | 13 h approx. | | | |
| | Run Time (full payload) | 10 h approx. | | | |
| | Maximum Speed | 1200 mm/s | | | |
| | Maximum Rotation Speed | 120 °/s | | | |
| Mobility | Stop Position Repeatability (single AMR) *3 | To a position: ±75 mm To standard target: ±25 mm, ±2° With CAPS: ±8 mm, ±0.5° With HAPS: ±8 mm, ±0.4° | | | |
| | Stop Position Repeatability (Fleet) *3 | To a position: ±100 mm To standard target: ±35 mm, ±2° With CAPS: ±14 mm, ±0.6° With HAPS: ±10 mm, ±0.6° | | | |
| Drive wheel | Materials | Aluminum with polyurethane tread | | | |
| Passive caster | Materials | Elastomer (Polyurethane) | | | |
| Auxiliary Power | | 5 VDC±5%, 1 A switched Aux power 12 VDC±5%, 1 A switched Aux power 20 VDC±5%, 1 A switched Aux power 22 to 30 VDC, 4 A switched × 2 22 to 30 VDC, 10 A switched 22 to 30 VDC, 10 A safe, switched 10 A switched and 10 A safe switched are drawn from the same source, and pass through the same 10 A fuse, so the sum of their current must be less than 10 A. | | | |

profiles.

*2. AMR maximum speed is recommended for traversing gaps, and routine driving over gaps should be avoided. Lower speeds may not traverse the gap. Faster or frequent driving over gaps will shorten the lifespan of the drivetrain components.

*3. Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

| | Item | LD-250 | | | |
|-----------------|-----------------------|---|--|--|--|
| | AMR | EN ISO 12100, EN ISO 13849-1, EN 60204-1, EN 1525, ANSI B56.5, ISO 10218/CSA Z434, EN 61000-6-2, EN 61000-6-4 | | | |
| Standards | Battery | EN ISO 12100, UN 38.3, EN 61000-6-2, EN 61000-6-4, UL 2271 | | | |
| | Docking Station | EN ISO 12100, UL1012/CSA C22.2.107.2, IEC 60204-1, EN 61000-6-2, EN 61000-6-4 | | | |
| | Wireless | IEEE 802.11 a/b/g | | | |
| Safety Features | Safety Scanning Laser | One at front of AMR Class 1 PLd safety per ISO13849-1 240° field of view | | | |
| | E-STOP Buttons | One at Operator Panel, one on each side. Additional E-STOP buttons can be added the payload structure | | | |
| | Rear Sensing | Time of flight (TOF) sensors | | | |
| | Audible Indicators | Two speakers are included. Additional buzzers can be added | | | |
| Operator | Display | 3.5 inch TFT, 320 x 240 pixels, color screen | | | |
| Interface | Button | ON button, OFF button, Brake-release button, and keyed mode selection | | | |
| | Wireless | 802.11 a/b/g | | | |
| | Ethernet | One TCP/UDP interface (maintenance LAN), Auto-MDIX | | | |
| User Interface | Serial | Two serial communication interfaces | | | |
| | Digital I/O | 16 inputs, 16 outputs | | | |
| | Audio | Digital audio in / out | | | |

^{*1.} A speed of 600 mm/s is recommended for traversing steps, and routine driving over steps should be avoided. Lower speeds may not traverse the step. Faster or frequent driving over steps and gaps will shorten the lifespan of the drivetrain components. All steps should have smooth,

^{*2.} AMR maximum speed is recommended for traversing gaps, and routine driving over gaps should be avoided. Lower speeds may not traverse the gap. Faster or frequent driving over gaps will shorten the lifespan of the drivetrain components.
*3. Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

Virtual Fleet Manager Software Minimum Hardware Requirements

| Fleet Size / AMR Count | Small / ≤ 5 | Medium ≤ 15 | Large ≤ 30 | X-Large ≤ 100 |
|------------------------|-----------------------|----------------|---------------|------------------|
| Virtual CPU | 2 cores | | 4 cores | |
| Clockspeed | 4GHz | 8 GHz | 12 GHz | 16 GHz |
| Virtual RAM | 8 GB | 16 GB | 24 GB | 32 GB |
| Virtual Disk | 512 GB 1 TB | | | 1 TB |
| FLOW software version | Minimum FLOW Core 4.0 | | | |

Note: The PC/IPC/Server is supplied by the user.

EM2100 Appliance

| Linz 100 Appliance | |
|-------------------------------------|---|
| Weight | 9.1 kg |
| Mounting method | 1U rack mount in a standard 19-inch equipment rack |
| Power Supply | 100 to 240 VAC (typical 100 W) |
| Power Consumption | 200 W max. |
| Operating Temperature | 10 to 35°C |
| Storage Temperature | -25 to 60°C |
| Operating Humidity | 8 to 90%, non-condensing |
| Storage Humidity | 5 to 95%, non-condensing |
| Chassis Ingress Protection Class | IP20 |
| CPU | Intel® Xeon® CPU |
| Main Memory | 32 GB DDR3 |
| Storage | 60 GB SSD |
| Archive Storage | 4 TB HDD |
| Communication ports | Four 10/100/1000 Ethernet Four USB One VGA |
| Status Display | Multi-segment LCD |

| High Accuracy Positioning System (HAPS) | | |
|---|--------------------------------|--|
| Sensor | Depth | 30 mm |
| | Width | 160 mm |
| | Ingress Protection Class | IP64 |
| | Environment | -40 to 85°C |
| | LEDs | Power, tape present, left marker, right marker |
| Magnetic Tape | Width | 25 mm |
| wagnetic rape | Orientation | South up |
| | Width | 25 mm |
| Markers | Length | 300 mm min. for 500 mm/s drive speed |
| (Magnetic Tape) | Orientation | North up |
| ι αρε) | Separation From Tape | 15 to 30 mm |
| | Front Sensor | RS232-1 (/dev/ttyUSB9) on the core |
| Connections | Rear Sensor | RS232-2 (/dev/ttyUSB10) on the core |
| | Power, Both Sensors | Aux power using the included splitter cable |
| Stop Position | Single AMR | ±8 mm position, 0.4° rotation |
| Repeatability, LD-60, LD-90 * | Fleet | ±10 mm position, 0.5° rotation |
| Stop Position | Single AMR | ±8 mm position, 0.4° rotation |
| Repeatability, LD-250 * | Fleet | ±10 mm position, 0.6° rotation |

 $[\]ensuremath{\bigstar} \ensuremath{\mathsf{Stop}} \ensuremath{\mathsf{position}} \ensuremath{\mathsf{repeatability}} \ensuremath{\mathsf{values}} \ensuremath{\mathsf{were}} \ensuremath{\mathsf{obtained}} \ensuremath{\mathsf{using}} \ensuremath{\mathsf{default}} \ensuremath{\mathsf{AMR}}$ parameters and a map created by the LD-series AMR.

| Cell Alignment Positioning System (CAPS) | | |
|---|------------|--------------------------------|
| Stop Position | Single AMR | ±8 mm position, 0.5° rotation |
| Repeatability, LD-60, LD-90, LD-90x * | Fleet | ±12 mm position, 0.5° rotation |
| Stop Position | Single AMR | ±8 mm position, 0.5° rotation |
| Repeatability, | Fleet | ±14 mm position, 0.6° rotation |

* Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

Software license

Battery

LD-250 * Type

| Dattory | |
|-----------------------------|--------------------------------------|
| Туре | Lithium-Ion (LiFePO4) |
| Weight | 19 kg |
| Voltage | 22 to 30 VDC (25.6 VDC nominal) |
| Capacity | 72 Ah (battery cell nominal) |
| Recharge Time | 2 hrs. 10 min. for 20% to 80% charge |
| Ingress Protection Class | IP20 |
| Recharge Cycles | Approximately 2000 cycles * |
| Charging Method | Automatic or manual |
| | |

*Approximately 80% of nominal battery capacity will be available after using the battery at 90% depth of discharge at temperatures between 15°C to 35°C, charging and discharging at a 1C rate.

Docking Station

| Docking Station | |
|--------------------------------------|---|
| Current | 8 A * |
| Power | 100 to 240 VAC, 50 to 60 Hz |
| Power Consumption | 800 W |
| Humidity | 5 to 95L%, non-condensing |
| Temperature | 5 to 40° C |
| Dimensions (W \times D \times H) | $349 \times 369 \times 315$ mm $495 \times 495.5 \times 317$ mm (with floor plate) |
| Weight | 8.2 kg |
| Mounting | Wall bracket, directly to floor, or on floor with floor plate |
| Indicators | Power on: blue Charging: yellow |
| Connector | For out-of-AMR battery charging |
| | |

* Circuit breaker built into AC power switch

Joystick (Pendant)

| Weight | 0.55 kg |
|-----------|---------|
| IP Rating | IP56 |

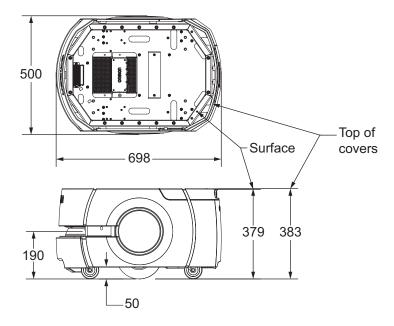
Acuity Localization

| Field of View | 140° |
|-------------------|---|
| Power Input | 12 VDC (±10%) supplied from AMR through power connector |
| Power Consumption | 3.3 W maximum |

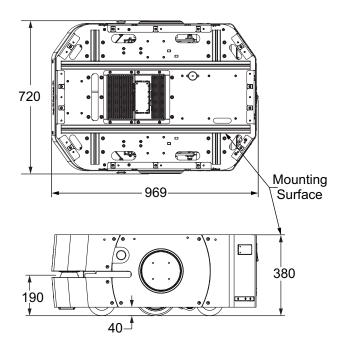
MobilePlanner Software

| CPU | 1.5 GHz dual-core CPU recommended |
|------------------------|--|
| Main Memory | 1.5 GB min. (4 GB min. recommended) |
| Hard Disk | At least 200 MB of available space |
| Video Memory | 256 MB min. |
| Display | XGA 1024 × 768, 16 million colors |
| Supported Languages | English, Japanese, German, French, Italian, Korean, Spanish, Polish, Simplified Chinese, Traditional Chinese |

LD-60, LD-90, LD-90x, LD-60 ESD, LD-90 ESD and LD-90x ESD

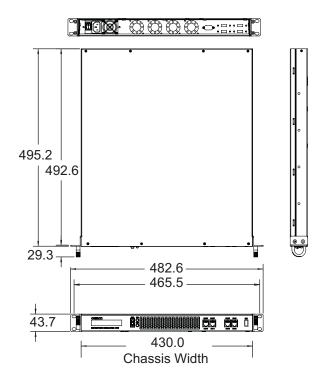


LD-250, LD-250 ESD

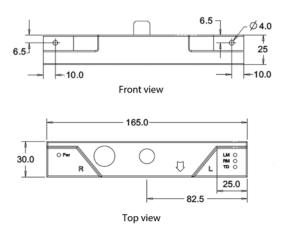


Dimensions (Unit: mm)

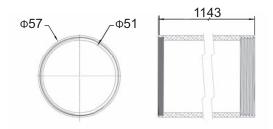
EM2100 Appliance



High Accuracy Positioning System (HAPS)

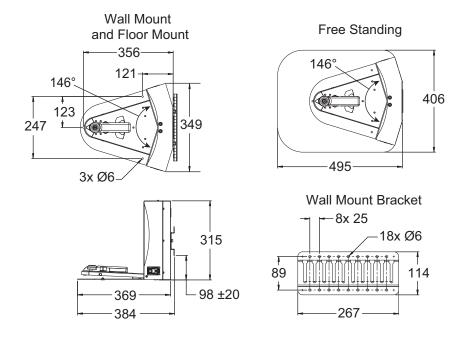


Acuity Localization

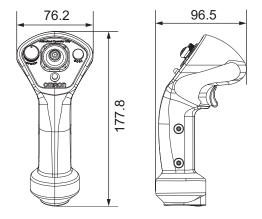


Dimensions (Unit: mm)

Docking Station



Joystick (Pendant)



Related Manuals

| Catalog Number | Manual Title |
|----------------|--|
| I611 | LD-60/90 Platform User's Manual |
| I613 | LD Platform Peripherals User's Guide |
| I614 | Mobile Robot Software Suite User's Guide |
| I615 | Enterprise Manager User Guide (this covers the EM1100, not the EM2100) |
| I616 | Mobile Robot LD Safety Guide |
| I617 | Advanced Robotics Command Language Reference Guide |
| I618 | Advanced Robotics Command Language Fleet Manager - Mobile Robots Integration Guide |
| 1634 | EM2100 Installation Guide |
| 1635 | Fleet Operations Workspace Core User's Manual |
| 1636 | Fleet Operations Workspace Core Migration Guide |
| 1637 | Fleet Operations Workspace Core Integration Toolkit User Guide |
| 1665 | Fleet Operations Workspace iQ User's Manual |
| 1649 | Fleet Simulator User's Manual |
| 1695 | Virtual Fleet Manager Installation Guide |
| 1642 | LD-250 Platform User's Manual |
| 1677 | Mobile I/O Box User's Manual |
| 1680 | LD-Series Integration Guide |

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